

Lecture 5. A3 – Homogenous Linear Second-Order Differential Equations.

A. Linear Second–Order Differential Equations.

A differential equation is **second–order linear** if it can be put into form:

and is further **homogeneous** if:

For the time being we will concentrate on the **homogeneous** subcategory.

For example:

$$t^2 y'' + 3ty' - 3y = 0$$

which we verify has among its solutions:

$$y_1 = t$$

$$y_2 = \frac{1}{t^3}$$

Functions y_1 and y_2 are **linearly independent** if:

Otherwise they are **linearly dependent**.

A **linear combination** of y_1 and y_2 has form:

$$y =$$

Show that if y_1 and y_2 solve the **homogeneous** linear:

$$y'' + p(t)y' + q(t)y = 0$$

then so does any linear combination $y = C_1 y_1 + C_2 y_2$.

A pair of solutions y_1 and y_2 to **homogeneous** 2nd–order linear ODE:

$$y'' + p(t)y' + q(t)y = 0$$

is called **fundamental set of solutions** if they are:

Theorem: In this case the general solution has form:

$$y =$$

Remember second–order means only up to the second derivative appears. Linear means y, y', y'' appear linearly.

We call this form **standard form**. The right side $f(t)$ is commonly referred to as the **forcing term**.

Linear independence and linear combinations are notion from linear algebra. There is a definition of linear independence for a list of more than two functions, but it is a little more complicated. It requires that no function in that list is a linear combination of other functions in that list.

Be careful: this result only applies in the **homogeneous** case!

Again: be warned this only applies in the homogeneous case! And really: added to the hypotheses should be that the functions $p(t)$ and $q(t)$ are “nice” in the sense that they are continuous on the interval in which the solution is being considered.

Example 1. Find the solution to the initial value problem:

$$t^2 y'' + 3ty' - 3y = 0 \text{ with } y(1) = 0 \text{ and } y'(1) = 4$$

using that a fundamental set of solutions $y_1 = t$ and $y_2 = \frac{1}{t^3}$.

B. Wronskian.

The **Wronskian** of function y_1 and y_2 is:

$$W(y_1, y_2) =$$

This is an example of a **determinant**:

$$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

Suppose y_1 and y_2 are linearly dependent: for example $y_2 = cy_1$.

$$W(y_1, cy_1) =$$

Functions y_1 and y_2 are linearly independent if and only if:

$$W(y_1, y_2) \neq$$

Really this result is only true for “nice” functions y_1 and y_2 . Thankfully, the functions we obtain from solving homogeneous linear differential equations are always “nice” enough.

Suppose now that y_1 and y_2 are solutions to homogeneous:

$$y'' + p(t)y' + q(t)y = 0$$

Show that $W = W(y_1, y_2)$ satisfies the differential equation:

$$(\ln W)' = -p(t)$$

Abel’s Theorem. If y_1 and y_2 are solutions to:

$$y'' + p(t)y' + q(t)y = 0$$

then:

$$W(y_1, y_2) =$$

A function of the form Ce^{stuff} either **always** has value 0 (if $C = 0$) or **never** has value 0 (if $C \neq 0$). This is because exponentials never have value 0.

Example 2. For the solutions $y_1 = t$ and $y_2 = \frac{1}{t^3}$ of the differential equation:

$$t^2 y'' + 3ty' - 3y = 0$$

compute their Wronskian and confirm Abel's Theorem.