A. **Matrix Inverses.** We said that the matrix product does not have the cancellation property. However there are **special** matrices that can be cancelled.

A matrix A is **invertible** if it has an **inverse** matrix  $A^{-1}$  so that:

The inverse is like the 'cancelling' of A.

Inverses of  $2 \times 2$  Matrices.

The inverse of 
$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
 is  $A^{-1} =$ 

The denominator is called the **determinant** of A:

$$\det A = \det \begin{pmatrix} a & b \\ c & d \end{pmatrix} =$$

and the matrix is invertible if and only if:

 $2 \times 2$  means 2 rows and 2 columns.

Note in the formula for the inverse: the entries on the main diagonal (from upper–left to bottom–right) are swapped, and the other entries have their sign flipped.

**Example 1.** Use matrix inverses to solve the system:

$$\begin{cases} 2x + 3y = 5\\ 3x + 9y = 2 \end{cases}$$

The general strategy is:

**Step 1.** Write in matrix form Ax = b.

**Step 2.** Find  $A^{-1}$  if possible. If not possible, since det A = 0, then the system either is inconsistent or has free variables.

**Step 3.** Multiply the equation by  $A^{-1}$  to solve for the unique solution  $\mathbf{x} = A^{-1}\mathbf{b}$ .

## B. Eigenstuff.

An **eigenvector** of a square matrix **A** is a **nonzero** column vector **v** to that:

 $A\mathbf{v} =$ 

where  $\lambda$  is a scalar called the **eigenvalue** of A corresponding to v.

For example confirm that:  $\mathbf{v} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$  is an eigenvector of  $\mathbf{A} = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix}$ 

**Square** means the same number of rows as columns.

The definition may seem random now, but will turn out to be very useful in solving systems of differential equations.

In words: multiplying A by an eigenvector scales the eigenvalue by a factor of  $\lambda$ .

How do we locate eigenvalues and eigenvectors? We solve:

 $A\mathbf{x} = \lambda \mathbf{x}$ 

The idea is that  $(A - \lambda I)x = 0$  always has solution x = 0. For it to have another solution (which would be an **eigenvector** of A) then  $A - \lambda I$  cannot be invertible, otherwise we could 'cancel' it to conclude it must be the case that x = 0.

## Finding Eigenstuff.

The eiegenvalues are A are solutions to the characteristic equation:

and the corresponding eigenvectors are found by solving:

We call  $\det(A - \lambda I)$  the **characteristic polynomial** because, as we will see, it turns out to be a polynomial in variable  $\lambda$ .

**Example 2.** Find the eigenvalues of A and an eigenvector for each eigenvalue:

$$A = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix}$$

**Step 1.** Solve the characteristic equation  $\det(A - \lambda I) = 0$  to find the eigenvalues.

Step 2. For each eigenvalue  $\lambda = c$ , find a nonzero solution to (A-cI)x=0. There should always be a free variable, and you can find an eigenvector by setting the free variable to any **nonzero** value you like. There are infinite choices of eigenvectors, obtained by selecting different values for the free variable.