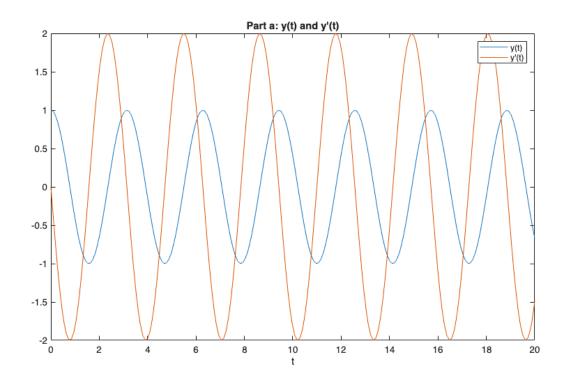
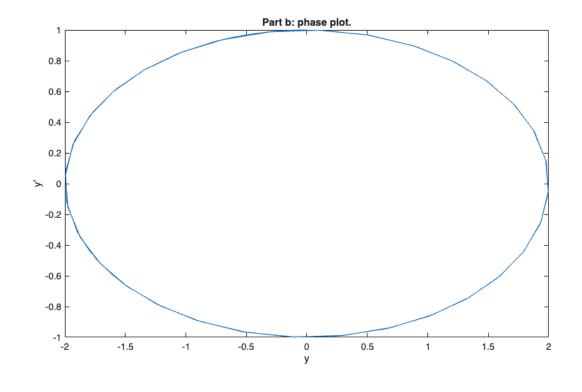
```
%=======Solution to Sim03Q1=======%
clc % clear command window
clear all % remove all variables from workspace
close all % close all figures
% given: y''+4y = 0
% set: y_1 = y
% set: y_2 = y'
% convert differential equation: y_2'+4y_1 = 0
% solve for y_2' = -4y_1
% obtain system:
% y_1' = y_2
y_2' = -4y_1
% define column vector f(t,[y_1;y_2]) = [y_2; -4y_1]
f = @(t,y) [y(2); -4*y(1)];
% define tspan 0 <= t <= 30
tspan = [0 20];
%-----%
% initial value y_1(0) = 1 and y_2(0) = 0 for solution
y0 = [1;0];
% solve dy/dt = f(t,y) with y(0) = [1;0]
[t,y] = ode45(f, tspan,y0);
% plot y and y' against t
figure % new figure window
plot(t,y(:,1)) % plot y(t) against t
hold on
plot(t,y(:,2)) % plot y'(t) against t
xlabel("t") % label the x-axis as t
legend("y(t)","y'(t)") % label the graphs in the order they were plotted
title("Part a: y(t) and y'(t)") % indicate that this is y and y' versus t
%-----%
% plot y' against y
figure % new figure window
plot(y(:,2),y(:,1)) % plot y'(t) against y(t)
xlabel("y") % label the x-axis as y
ylabel("y'") % label the y-axis as y'
title("Part b: phase plot.") % indicate that this is the phase plot
%-----%
% redefine initial values y_1(0) = 2 and y_2(0) = 0 for solution
y0 = [2;0];
```

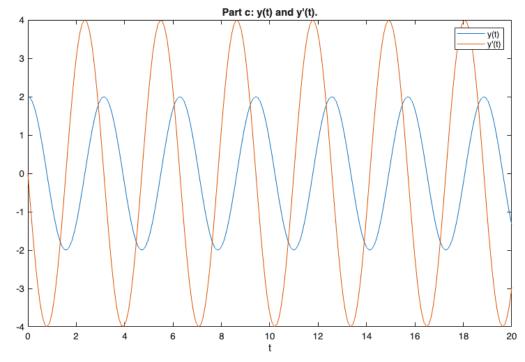
```
% solve dy/dt = f(t,y) with y(0) = [1;0]
[t,y] = ode45(f, tspan,y0);

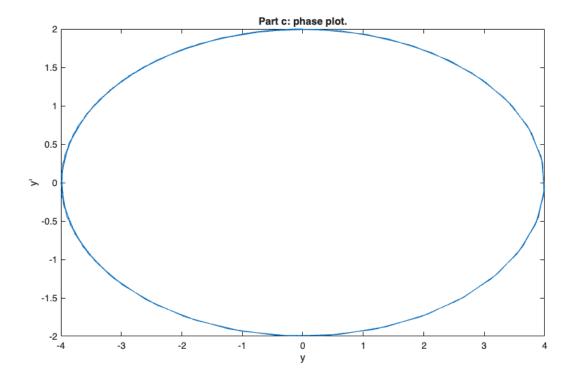
% plot y and y' against t
figure % new figure window
plot(t,y(:,1)) % plot y(t) against t
hold on
plot(t,y(:,2)) % plot y'(t) against t
xlabel("t") % label the x-axis as t
legend("y(t)","y'(t)") % label the graphs in the order they were plotted
title("Part c: y(t) and y'(t).") % indicate that this is y and y' versus t

% plot y' against y
figure % new figure window
plot(y(:,2),y(:,1)) % plot y'(t) against y(t)
xlabel("y") % label the x-axis as y
ylabel("y") % label the y-axis as y'
title("Part c: phase plot.") % indicate that this is the phase plot
```





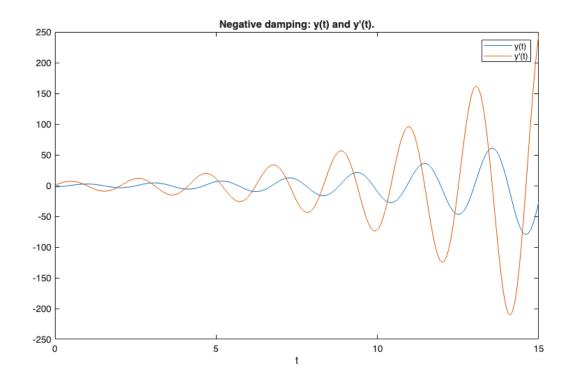


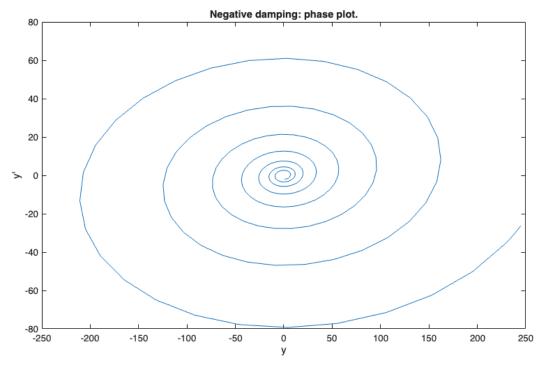


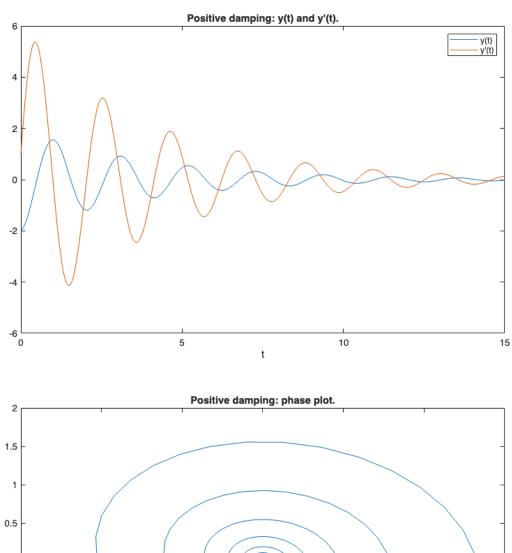
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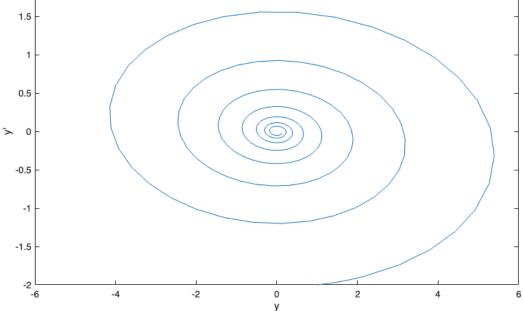
```
%=======Solution to Sim03Q2========%
clc % clear command window
clear all % remove all variables from workspace
close all % close all figures
% given: 16y''+ay'+145y = 0
% set: y_1 = y
% set: y_2 = y'
% convert differential equation: 16y_2'+ay_2+145y 1 = 0
% solve for y_2' = -(145/16)y_1-(a/16)y_2
% obtain system:
% y_1' = y_2
y 2' = -(145/16)y_1-(a/16)y_2
% define column vector f(t,[y 1;y 2]) = [y 2; -(145/16)y 1-(a/16)y 2]
f = (t,y,a) [y(2); -(145/16).*y(1)-(a/16).*y(2)];
% define tspan 0 <= t <= 15
tspan = [0 15];
% initial value y 1(0) = -2 and y 2(0) = 1 for solution
y0 = [-2;1];
%-----%
% negative damping: a = -8
fnegdamp = @(t,y) f(t,y,-8)
% solve dy/dt = f(t,y) with y(0) = [-2;1]
[t,y] = ode45(fnegdamp, tspan,y0);
% plot y and y' against t
figure % new figure window
plot(t,y(:,1)) % plot y(t) against t
hold on
plot(t,y(:,2)) % plot y'(t) against t
xlabel("t") % label the x-axis as t
legend("y(t)","y'(t)") % label the graphs in the order they were plotted
title("Negative damping: y(t) and y'(t).") % indicate that this is y and y'
versus t
%-----%
% plot y' against y
figure % new figure window
plot(y(:,2),y(:,1)) % plot y'(t) against y(t)
xlabel("y") % label the x-axis as y
ylabel("y'") % label the y-axis as y'
title("Negative damping: phase plot.") % indicate that this is the phase plot
%----%
```

```
% positive damping: a = 8
fposdamp = @(t,y) f(t,y,8)
% solve dy/dt = f(t,y) with y(0) = [1;0]
[t,y] = ode45(fposdamp, tspan,y0);
% plot y and y' against t
figure % new figure window
plot(t,y(:,1)) % plot y(t) against t
hold on
plot(t,y(:,2)) % plot y'(t) against t
xlabel("t") % label the x-axis as t
legend("y(t)","y'(t)") % label the graphs in the order they were plotted
title("Positive damping: y(t) and y'(t).") % indicate that this is y and y'
versus t
% plot y' against y
figure % new figure window
plot(y(:,2),y(:,1)) % plot y'(t) against y(t)
xlabel("y") % label the x-axis as y
ylabel("y'") % label the y-axis as y'
title("Positive damping: phase plot.") % indicate that this is the phase plot
fnegdamp =
  function_handle with value:
    \theta(t,y)f(t,y,-8)
fposdamp =
  function_handle with value:
    \theta(t,y)f(t,y,8)
```









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